Benchmarking a Variant of CMAES-APOP on the BBOB Noiseless Testbed

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- The CMAES-APOP algorithm
- A Variant of CMAES-APOP algorithm
- Numerical Experiments on the BBOB Noiseless Testbed
- Conclusion and Perspectives

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The CMAES-APOP algorithm

• Adapting population size seems to be a right way in the CMA-ES to optimize multi-modal functions.

- Some approaches for adapting population size in the CMAES:
 - IPOP-CMA-ES¹ [AH05, Ros10]: the CMA-ES is restarted with increasing population size by a factor of two whenever one of the stopping criteria is met.
 - BIPOP-CMA-ES ²: define two restart regimes: one with large populations (IPOP part), and another one with small populations. In each restart, BIPOP-CMA-ES selects the restart regime with less function evaluations used so far.

¹[AH05] A. Auger and N. Hansen, A restart cma evolution strategy with increasing population size, 2005 IEEE Congress on Evolutionary Computation, vol. 2, 2005, pp. 1769-1776.

²[Han09] N. Hansen, Benchmarking a bi-population cma-es on the bbob-2009 function testbed, Proceedings of the 11th Annual Conference Companion on Genetic and Evolutionary Computation Conference: Late Breaking Papers, GECCO 09, 2009, pp. 2389-2396.

- Ahrari and Shariat-Panahi ³: An adaptation strategy for the CMA-ES which used the oscillation of objective value of x_{mean} to quantify multimodality of the region under exploration.
- Nishida and Akimoto ⁴: An adaptation strategy for the CMA-ES that is based on the estimation accuracy of the natural gradient.

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³[ASP15] A. Ahrari and M. Shariat-Panahi, An improved evolution strategy with adaptive population size, Optimization 64 (2015), no. 12, 2567-2586.

⁴[NA16] K. Nishida and Y. Akimoto, Population size adaptation for the cma-es based on the estimation accuracy of the natural gradient, Proceedings of the Genetic and Evolutionary Computation Conference 2016, GECCO 16, 2016, pp. 237-244 = 100 - 2000

The CMAES-APOP Algorithm ⁵

Motivation

- a natural desire when solving any optimization problem
- one prospect when using larger population size to search "We want to see the decrease of objective function"

Signal?

- We track the non-decrease of objective function (exactly, $f^{\text{med}} := \text{median}(f(\mathbf{x}_{i:\lambda}), i = 1, ..., \mu)$ - the median of objective function of μ elite solutions in each iteration) in a slot of S successive iterations to adapt the population size in the next S successive iterations
- We do not adapt the population size in each iteration but in each slot of *S* iterations.

⇒ The variation of population size takes a staircase form in iterations. ⁵[NH17] D. M. Nguyen and N. Hansen, Benchmarking cmaes-apop on the bbob noiseless testbed, Proceedings of the Genetic and Evolutionary Computation Conference Companion (New York, NY, USA), GECCO 17, ACM, 2017, pp. d1756-1763. = 0.000

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Ideas: $f^{\text{med}} := \text{median}(f(\mathbf{x}_{i:\lambda}), i = 1, ..., \mu)$ is the 25th percentile of objective function values evaluated on λ candidate points. \Rightarrow What if we change the 25th percentile to the other percentiles?

Some test functions:

$$f_{\text{Rastrigin}}(\mathbf{x}) = 10n + \sum_{i=1}^{n} (x_i^2 - 10\cos(2\pi x_i))$$

$$f_{\text{Schaffer}}(\mathbf{x}) = \sum_{i=1}^{n-1} (x_i^2 + x_{i+1}^2)^{0.25} [\sin^2(50(x_i^2 + x_{i+1}^2)^{0.1}) + 1]$$

$$f_{\text{Ackley}}(\mathbf{x}) = 20 - 20 \cdot \exp\left(-0.2\sqrt{\frac{1}{n}\sum_{i=1}^{n} x_i^2}\right) + e - \exp\left(\frac{1}{n}\sum_{i=1}^{n}\cos(2\pi x_i)\right)$$

$$E_{\text{Bohachevsky}}(\mathbf{x}) = \sum_{i=1}^{n-1} (x_i^2 + 2x_{i+1}^2 - 0.3\cos(3\pi x_i) - 0.4\cos(4\pi x_{i+1}) + 0.7)$$

- For each function, 51 runs are conducted.
- $f_{\text{stop}} = 10^{-10}$ ($f_{\text{stop}} = 10^{-8}$ for the Schaffer function).
- the starting point for the functions Rastrigin, Schaffer, Ackley, Bohachevsky is (5, ..., 5), (55, ..., 55), (15, ..., 15), and (8, ..., 8) respectively; the initial step-size σ for these functions is 2, 20, 5, 3 respectively.

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We run the CMAES-APOP algorithm with the small initial population size $\lambda = \lambda_{default}$ (i.e, set $k_n = 1$) and without the upper bound for the population size in three dimensions n = 10, 20, 40.

Function	n	25-р	1-p	10-p	50-p	75-p	90-p
Rastrigin	10	3.317e+04	4.332e+04	3.527e+04	3.160e+04	3.069e+04	3.250e+04
	20	9.077e+04	1.189e+05	9.254e+04	9.212e+04	9.038e+04	9.286e+04
	40	2.981e+05	3.992e+05	3.163e+05	3.006e+05	3.034e+05	3.133e+05
Schaffer	10	3.098e+04	5.111e+04	3.334e+04	3.051e+04	3.012e+04	3.147e+04
	20	8.175e+04	1.663e+05	8.833e+04	8.024e+04	8.233e+04	8.646e+04
	40	2.255e+05	4.942e+05	2.266e+05	2.224e+05	2.348e+05	2.325e+05
Ackley	10	1.403e+04	2.280e+04	1.481e+04	1.369e+04	1.429e+04	1.498e+04
	20	3.105e + 04	6.125e+04	3.263e+04	3.024e+04	3.144e+04	3.326e+04
	40	7.204e+04	1.275e+05	7.379e+04	6.761e+04	7.164e+04	7.617e+04
Bohachevsky	10	1.002e+04	1.494e+04	1.052e+04	1.015e+04	1.064e+04	1.085e+04
	20	2.397e+04	4.261e+04	2.533e+04	2.366e+04	2.378e+04	2.494e+04
	40	5.536e+04	9.881e+04	5.781e+04	5.627e+04	5.810e+04	6.101e+04

Table: The aRT of some variants of CMAES-APOP: the 25-percentile is replaced by the other percentiles (aRT (average Running Time) = number of function evaluations divided by the number of successful trials)

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Some notations:

- P : a set of percentiles.
- f^p := percentile({f(x_{i:λ}), i = 1, ..., λ}, p) : the p-percentile of objective function of λ candidates in each iteration, where p can vary from 0 to 100 (in fact p will be chosen from the set of percentiles P); f^p_{prev} and f^p_{cur} denote the p-percentiles in the previous and current iteration respectively.
- n_{up} : the number of times " $f_{cur}^p f_{prev}^p > 0$ " occurs during a slot of S iterations.
- t_{up} : the history of n_{up} in each slot recorded.
- $\bullet\ no_{up}$: the number of most recent slots we do not see the non-decrease.
- $\lambda_{\max} := (20n + 30)\lambda_{default}$: the maximum number of the population, where $\lambda_{default} = \lfloor 4 + 3\log(n) \rfloor$.

```
(1) Input: \mathbf{m} \in \mathbb{R}^n, \sigma \in \mathbb{R}_+
      Initialize: C = I, \mathbf{p}_c = 0, \mathbf{p}_{\sigma} = 0, \lambda = k_n \times \lambda_{default}
     Set: \mu = |\lambda/2|, w_i, \mu_w, c_c, c_\sigma, c_1, c_\mu, d_\sigma, iter = 0, S = 5, r_{max} = 30, n_{up} = 0, t_{up} = [].
     While not terminate
4
           iter = iter + 1:
           \mathbf{x_i} = \mathbf{m} + \sigma \mathbf{y_i}, \mathbf{y_i} \sim \mathbf{N}(\mathbf{0}, \mathbf{C}), \text{ for } i = 1, \dots, \lambda
           Take p randomly from the set of percentiles P
           if iter > 1
                if f_{cur}^p - f_{prev}^p > 0 //Check if f^p increases
                     n_{\rm up} = n_{\rm up} + 1;
                end
           end
           Update \mathbf{m}, \mathbf{p}_{c}, \mathbf{p}_{\sigma}, \mathbf{C}, \sigma as in the CMA-ES
           if (mod(iter, S) = 1) & (iter > 1) // Adapting the population size
                t_{up} = [t_{up}; n_{up}];
                Adapt the population size according to the information of n_{\rm HD} (... details in the next slide)
                n_{\text{up}} \leftarrow 0 // Reset n_{\text{up}} back to 0
           end
```

(16) Adapt the population size according to the information of n_{up} 16 1 if n > 1

16.1 If
$$h_{up} > 1$$

16.2 $\lambda \leftarrow \left[\min\left(\exp\left(\frac{n_{up}\cdot(4+3\log(n))}{S\cdot\sqrt{\lambda-\lambda_{default}+1}}\right), r_{max}\right) \times \lambda\right];$
16.3 $\lambda \leftarrow \min(\lambda, \lambda_{max});$
16.4 $\sigma \leftarrow \sigma \times \exp\left(\frac{1}{n}\left(\frac{n_{up}}{S}-\frac{1}{5}\right)\right);$ // Enlarge σ a little bit
16.5 elseif $n_{up} = 0$
16.6 $n_{up} = \text{length}(t_{up}) - \max(\text{find}(t_{up} > 0));$
16.7 if $\lambda > 2\lambda_{default}$
16.8 $\lambda \leftarrow \max(\lfloor\lambda \times \exp(-n_{up}/10))\rfloor, 2\lambda_{default});$
16.9 end
16.10 end
16.11 if λ is changed // Only when $n_{up} > 1$ or $n_{up} = 0$
16.12 Update $\mu, w_{i=1...\mu}, \mu_w$ w.r.t the new population size λ
16.13 Update the parameters $c_c, c_\sigma, c_1, c_\mu, d_\sigma$
16.14 end

Numerical Experiments on the BBOB Noiseless Testbed

- Test the algorithms with a budget of $2 \times 10^5 \times n$, where *n* is the problem dimension.
- Denote the variants corresponding to $P_1 = \{1, 25, 50\}$, $P_2 = \{1, 50\}$, and $P_3 = \{1, 50, 75\}$ by Var1, Var2 and Var3 respectively.
- In the first run: the pure CMA-ES with the default population size $\lambda = \lambda_{default}$. From second run: the pop-size adaptation strategy is applied with the initial population size $\lambda = k_n \times \lambda_{default}$.
- The parameter k_n is set to 10, 20, 30, 40, 50, 60 for n = 2, 3, 5, 10, 20, 40 respectively.
- Take the starting point \mathbf{m}^0 uniformly in $[-4,4]^n$.
- Set the initial step-size $\sigma_0 = 2$ for all run.

The variants < CMAES-APOP



All variants are still better than the IPOP-CMA-ES and BIPOP-CMA-ES on f3 in 10-D; than the BIPOP-CMA-ES on f19 in

dimensions 10; and than the BIPOP-CMA-ES on f_{20} in dimensions 20.

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The variants $>_{slightly}$ CMAES-APOP: f_{15} , f_{16} , f_{18} , f_{21} in 10-D



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The variants $>_{slightly}$ CMAES-APOP: f_7, f_8, f_{13}



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The variants > CMAES-APOP: on f_4 , f_{23} , f_{24} in small dimensions



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$(Var1 ({1, 25, 50}) \& Var3 ({1, 50, 75})) >_{slightly} Var2 ({1, 50})$



 \Rightarrow Tracking more percentiles can help us to make better decisions in adapting population size for the class of conditioned

 functions, and the class of multi-modal functions with adequate global structure in high dimensions.
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 Image: Comparison of the structure in high dimensions.
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$Var3 (\{1, 50, 75\}) >_{slightly} ((Var1 (\{1, 25, 50\}) \& Var2 (\{1, 50\})(1/2)$



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$\textbf{Var3} (\{1, 50, 75\}) >_{\textsf{slightly}} ((\textsf{Var1} (\{1, 25, 50\}) \And \textsf{Var2} (\{1, 50\})(2/2))$



 \Rightarrow The information of non-elite individuals is also useful to adapt the population

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Conclusion and Perspectives

Conclusion:

- Present a variant of CMAES-APOP: track the change of some percentiles of objective values rather than one percentile; set the upper bound of the population size depending on the problem dimension.
- This approach improves the performance of CMAES-APOP in some cases when the set of percentiles *P* is chosen appropriately.

Perspectives:

- How to initialize a good set *P* and how to evaluate the importance of each percentile *p* in *P* during the evolution process?
- The information of percentiles could play a deeper role inside the evolution process of the CMA-ES?

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Thank you for your attention!

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