

Benchmarking the Novel CMA-ES Restart Strategy Using the Search History on the BBOB Noiseless Testbed

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Introduction: CMA-ES with Restart Strategy

Covariance Matrix Adaptation Evolution Strategy (CMA-ES)

1. Generate candidate solutions $(x_i^{(t)})_{i=1,2,\dots,\lambda}$ from $\mathcal{N}(m^{(t)}, (\sigma^{(t)})^2 \mathbf{C}^{(t)})$
2. Evaluate $f(x_i^{(t)})$ and sort them, $f(x_{1:\lambda}) < \dots < f(x_{\lambda:\lambda})$.
3. Update the distribution parameters $\theta^{(t)} = (m^{(t)}, (\sigma^{(t)})^2 \mathbf{C}^{(t)})$ using the ranking of candidate solutions.

Restart strategies: almost necessities for multimodal black-box functions.

- **increasing the population size:** helpful for multimodal functions with well global structure
- **decreasing the initial step-size:** helpful for multimodal functions with weak global structure

Introduction: CMA-ES with Restart Strategy

Existing (successful) restart strategies:

IPOP: Doubles the population size every restart

effective on well-structured multimodal functions

BIPOP: IPOP regime + LS regime (start with a smaller step-size)

effective on well-structured multimodal functions (IPOP regime)

effective on weak-structured multimodal functions (LS regime)

Our Proposal: Utilizing the **Search History**

- to **early stop** overlapping restarts (new termination criterion)
- to **shrink the initial step-size** to prevent overlapping restarts

Search History

record the distribution parameters

History of Normalized Parameters

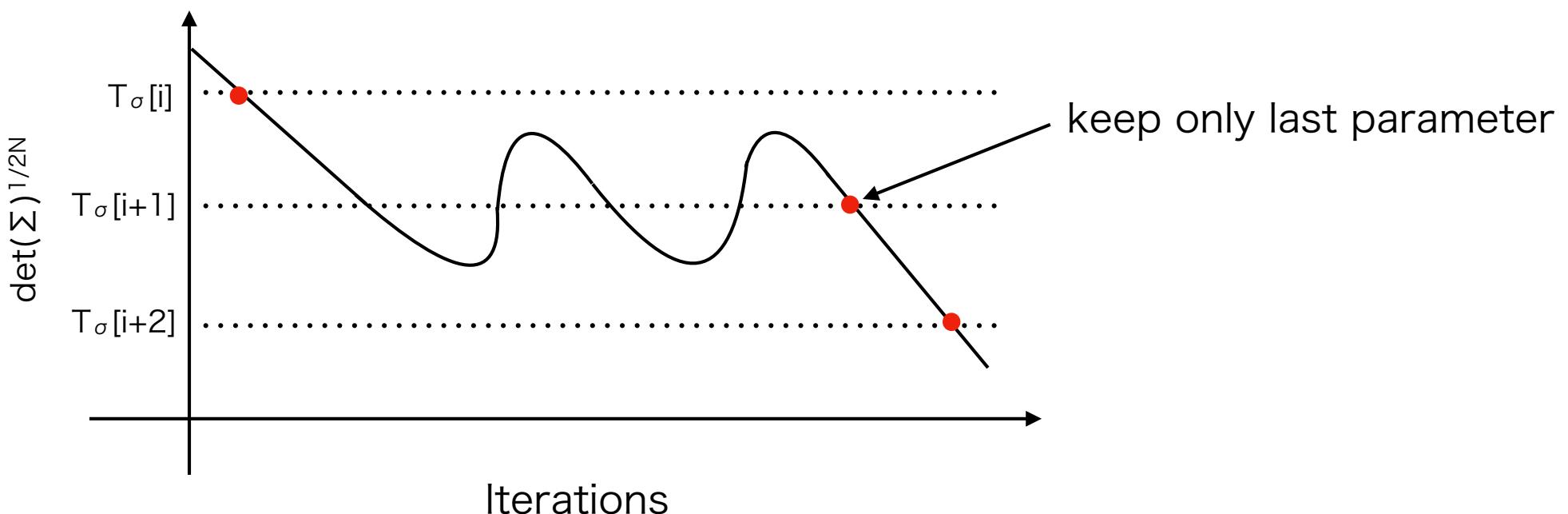
History of Normalized Distribution Parameters (\mathbf{m} , Σ)

\mathbf{m} : the mean vector

Σ : the normalized covariance matrix $\sigma^2\mathbf{C} / \alpha$ (α : normalization factor)

When to Record the Parameters?

- predefined target of $\det(\Sigma)^{1/2N}$: $T_\sigma = \det(\Sigma^{(0)})^{1/2N} \times [1, 10^{-1}, \dots]$
- every time $\det(\Sigma)^{1/2N}$ crosses $T_\sigma[i]$ from above



History of Normalized Parameters

After J restarts

#Restart	$T_\sigma[0]$	$T_\sigma[1]$...	$T_\sigma[k]$	$T_\sigma[k+1]$...	$T_\sigma[n_\sigma-1]$
1	(m, Σ)	(m, Σ)		(m, Σ)	(m, Σ)		(m, Σ)
2	(m, Σ)	(m, Σ)		(m, Σ)	-		-
:							
J	(m, Σ)	(m, Σ)		(m, Σ)	(m, Σ)		(m, Σ)

- at most J entries for each target $T_\sigma[k]$
- some entries are missing due to early termination

Termination Criterion Using Search History

detect and stop overlapping restarts

Termination Criterion: Basic Idea

After J restarts

#Restart	$T_\sigma[0]$	$T_\sigma[1]$...	$T_\sigma[k]$	$T_\sigma[k+1]$...	$T_\sigma[n_\sigma-1]$
1	(m, Σ)	(m, Σ)		(m, Σ)	(m, Σ)		(m, Σ)
2	(m, Σ)	(m, Σ)		(m, Σ)	-		-
:							
J	(m, Σ)	(m, Σ)		(m, Σ)	(m, Σ)		(m, Σ)

J+1st  
 Restart (m, Σ) (m, Σ) terminate!

#Restart	$T_\sigma[0]$	$T_\sigma[1]$...	$T_\sigma[k]$	$T_\sigma[k+1]$...	$T_\sigma[n_\sigma-1]$
1	close	far					
2	far	close					
:							
J	far	close					

- check if the current distribution is sufficiently **close** to the history
- terminate if they are regarded as **close** to the history n_{KL}^{check} times in a row

Termination Criterion: Similarity Check by KL-divergence

KL-divergence

$$D_{\text{KL}}(\mathcal{N}_0 \parallel \mathcal{N}_1) = \frac{1}{2} \{(m_1 - m_0)^T \Sigma_1^{-1} (m_1 - m_0) + \text{Tr}(\Sigma_0^{-1} \Sigma_1) - N + \ln \det(\Sigma_0^{-1} \Sigma_1)\}$$

Threshold for KL-divergence

- We want to detect if two distributions are optimizing the same Sphere

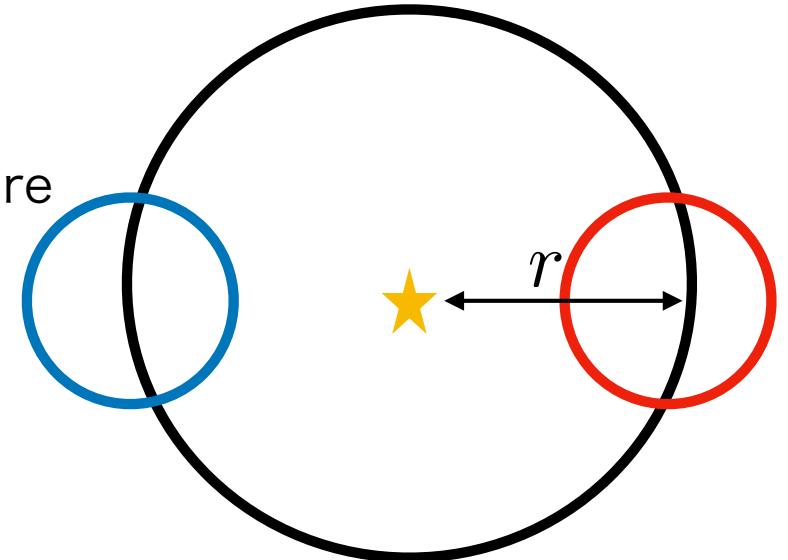
KL-divergence on Sphere

- Optimal Step-Size Case

$$\begin{aligned} D_{\text{KL}}(\mathcal{N}_0 \parallel \mathcal{N}_1) &= \frac{1}{2} (m_1 - m_0)^T \Sigma_1^{-1} (m_1 - m_0) \\ &= \frac{N^2 \alpha^2 \|m_1 - m_0\|^2}{2\beta^2 \mu_w^2 f(m_1)} = \frac{2N^2 \alpha^2 f(m_1)}{\beta^2 \mu_w^2 f(m_1)} = \frac{2}{\beta^2} \frac{N^2 \alpha^2}{\mu_w^2} \approx \frac{4}{\pi} \end{aligned}$$

Based on this derivation, we set $\delta_{\text{KL}}^{\text{thre}} = 2$.

- regarded as close if $\text{KL}(\mathcal{N}_0 \parallel \mathcal{N}_1) \leq \delta_{\text{KL}}^{\text{thre}} = 2$

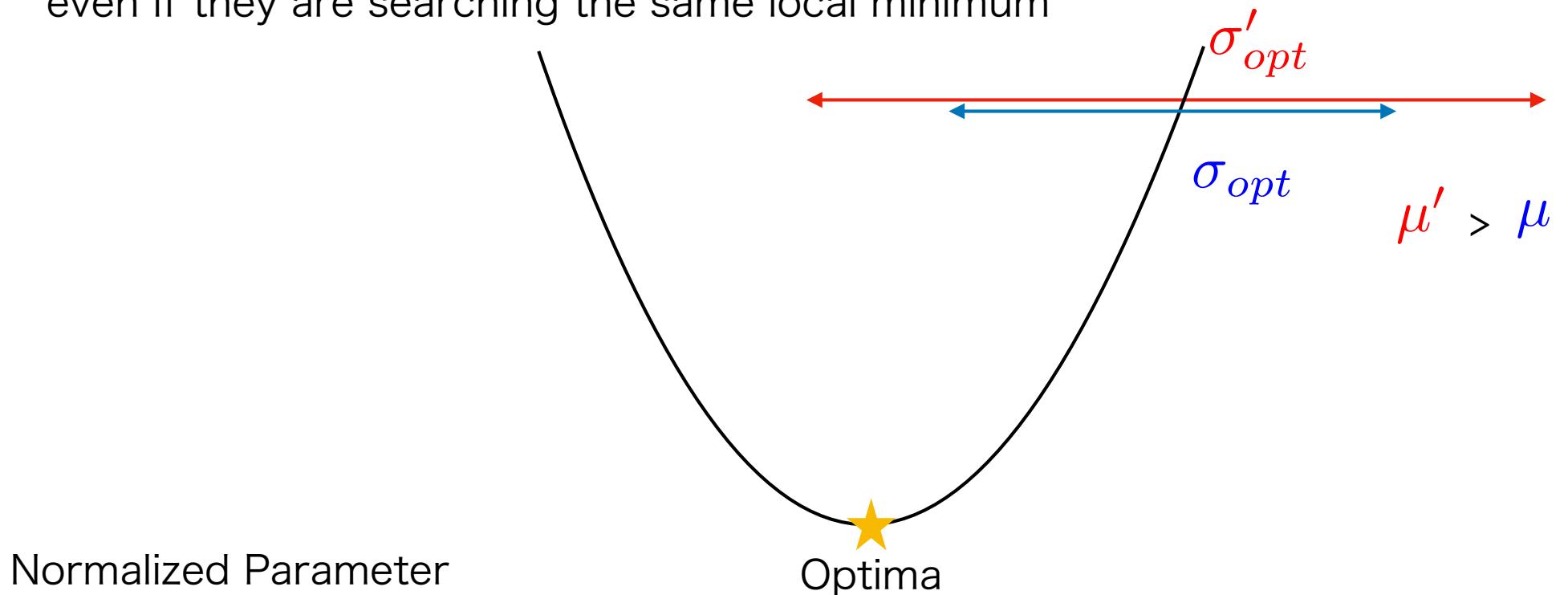


- ★ : optimal point
- : current distribution
- : distribution in the History

Normalization Factor α

Comparing two distributions with different population size?

- optimal step-size depends on the population size
- distributions won't be close
even if they are searching the same local minimum



$$\Sigma = \frac{\sigma^2}{\alpha^2} \mathbf{C} \quad \text{where} \quad \alpha = \frac{\mu_w}{N - 1 + \mu_w}$$

- reflect $\sigma^* \propto \mu_w = 1 / \sum_{i=1}^N w_i^2$ if $\mu_w \leq N$
- reflect σ^* tends to constant if $\mu_w \geq N$

Initial Step-Size Selection Using Search History

shrink the initial step-size
to prevent the overlapping search

Initial Normalized Step-Size Selection

Initial Step-Size Selection in BIPOP

- first run: $\sigma^{(0)}$
- IPOP regime: $\sigma^{(0)}$
- LS regime: $\sigma^{(0)} \times r$, r : random in $(0.01, 1)$

When to shrink the initial (normalized) step-size?

- overlapping restarts observed n_σ^{dec} times in a row
 - the current initial step-size is regarded as too large to escape from already searched big valley

How to shrink the initial (normalized) step-size?

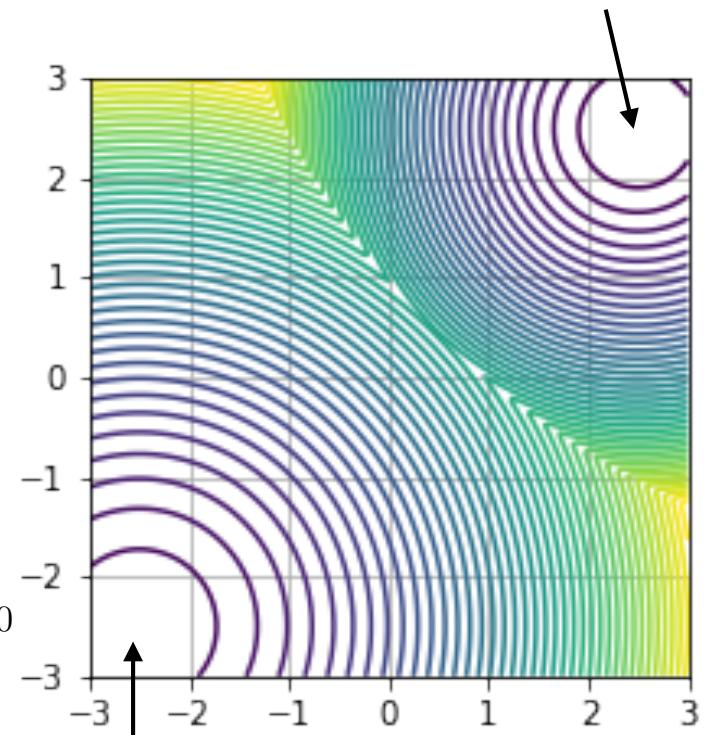
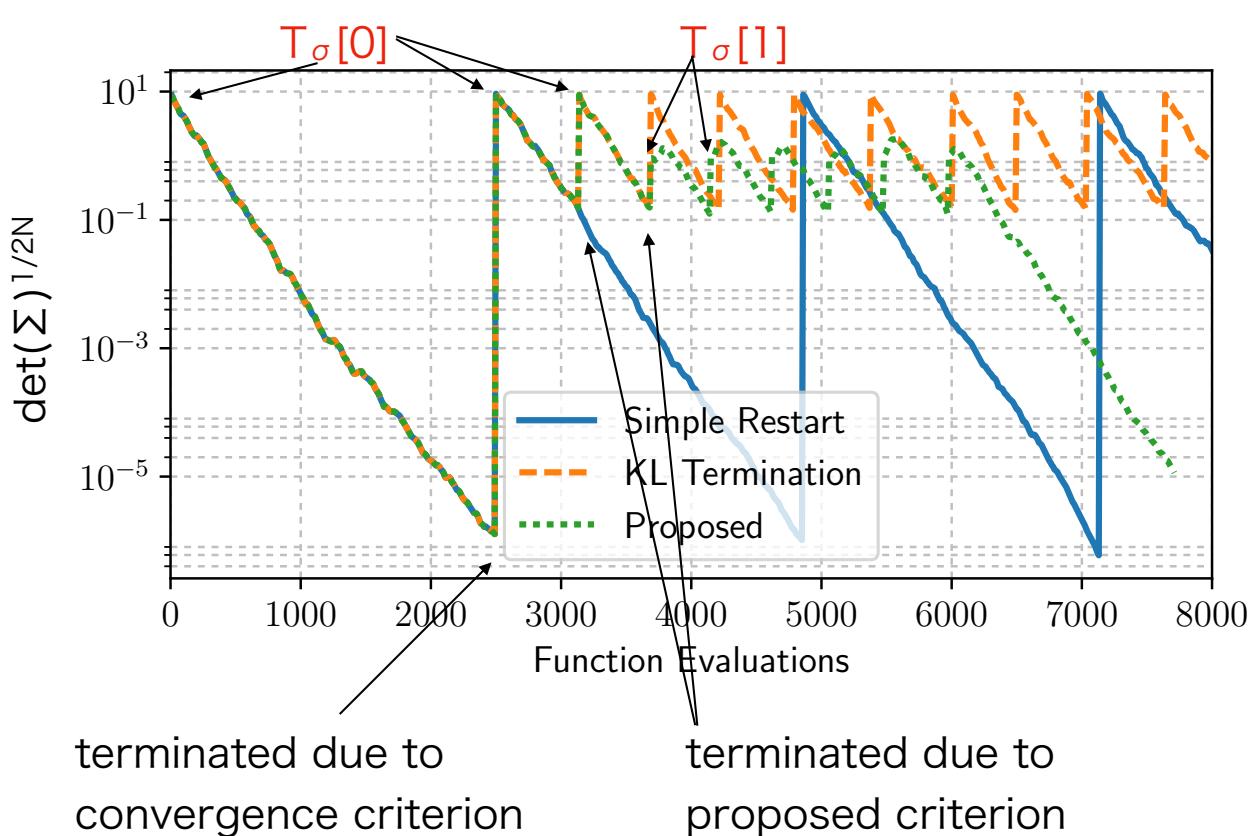
- first run: $\sigma^{(0)} = \alpha \times T_\sigma[0]$
- J^{th} run: $\sigma^{(0)} = \alpha \times T_\sigma[i]$
 - if overlapping restarts observed n_σ^{dec} times in a row: $\sigma^{(0)} = \alpha \times T_\sigma[i+1]$
 - if not: $\sigma^{(0)} = \alpha \times T_\sigma[i]$

Demonstration on Double-Sphere

$$f(x) = \min(a^2 \|x_o\|^2, \|x_l\|^2 + 1.0)$$

$$a = 1.5, x_o = x - [2.5, \dots, 2.5] \text{ and } x_l = x + [2.5, \dots, 2.5]$$

smaller basin of attraction
for global optimum



larger basin of attraction
for local optimum

BBOB Results

Termination Criteria

Termination Condition (Convergence Criteria)

tolf: $\text{median}(fiqr_hist) < 10^{-11}$

tolfrel: $\text{median}(fiqr_hist) < 10^{-12} * \text{abs}(\text{median}(fmin_hist))$

- ▶ the objective function value differences are too small to sort them without being affected by numerical errors.

tolx: $\text{median}(xiqr_hist) < 10^{-11}$

tolxrel: $\text{median}(xiqr_hist) < 10^{-12} * \text{abs}(\text{median}(xmin_hist))$

- ▶ the coordinate value differences are too small to update parameters without being affected by numerical errors.

Restart Scheme

	KL-Restart	KL-IPOP	KL-BIPOP	IPOP	BIPOP
Pop. Size	fixed λ_{def}^2	IPOP	BIPOP	IPOP	BIPOP
Init. σ	proposed	proposed	proposed	fixed	BIPOP
termination	convergence +proposed	convergence +proposed	convergence +proposed	convergence	convergence

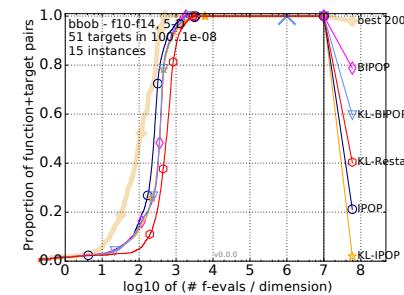
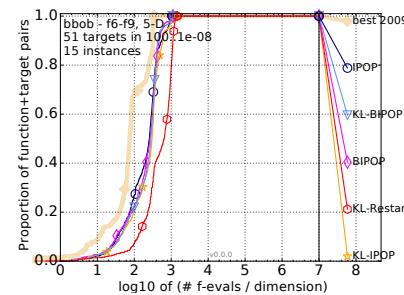
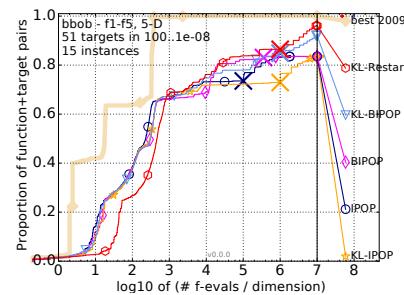
Maximum pop. size is $2^8 \times \lambda_{\text{def}}$ for IPOP regime

For each (re-)start of the algorithm, we initialize the mean vector $m \sim \mathcal{U}[-4, 4]^D$ and the covariance matrix $C = 2^2 I$. The maximum #f-call set to $10^6 D$.

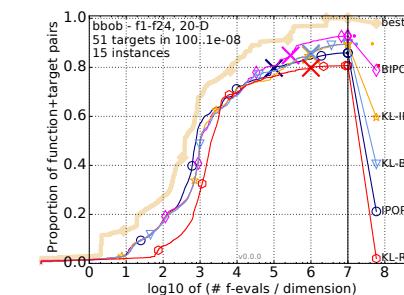
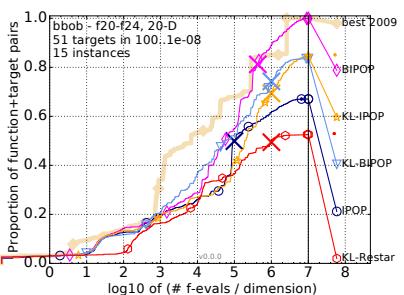
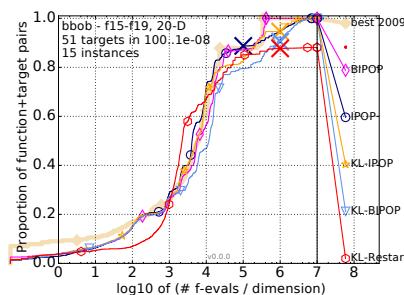
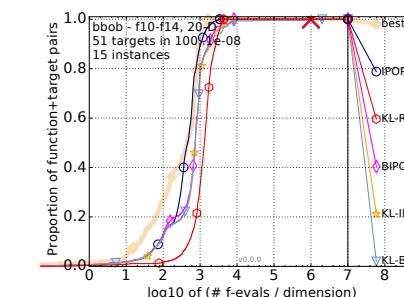
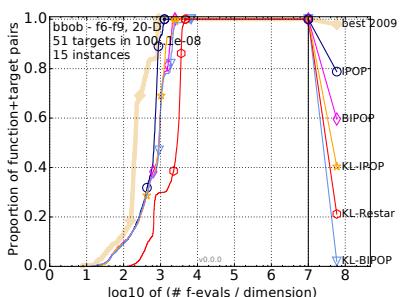
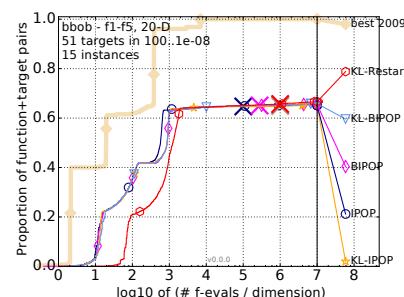
Data for IPOP and BIPOP are downloaded from the web page

Results on 5D and 20D

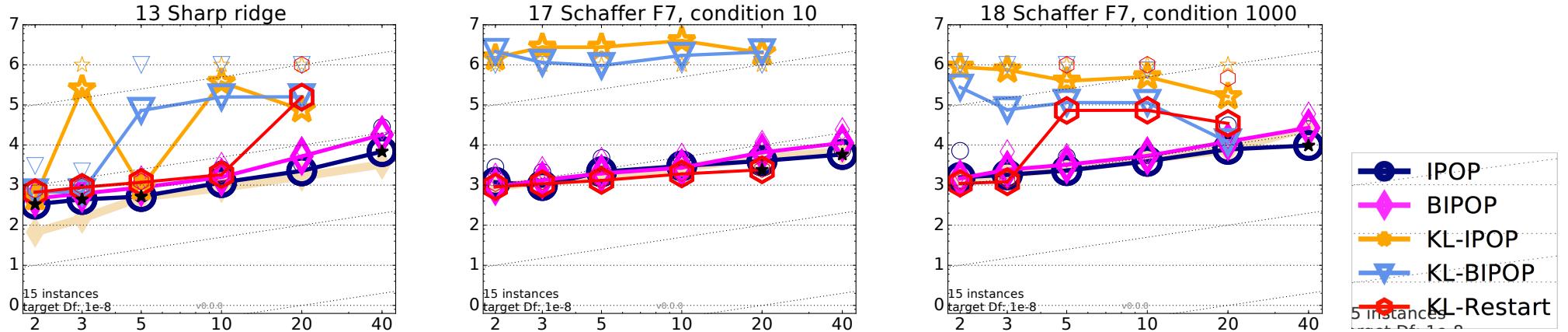
5D



20D

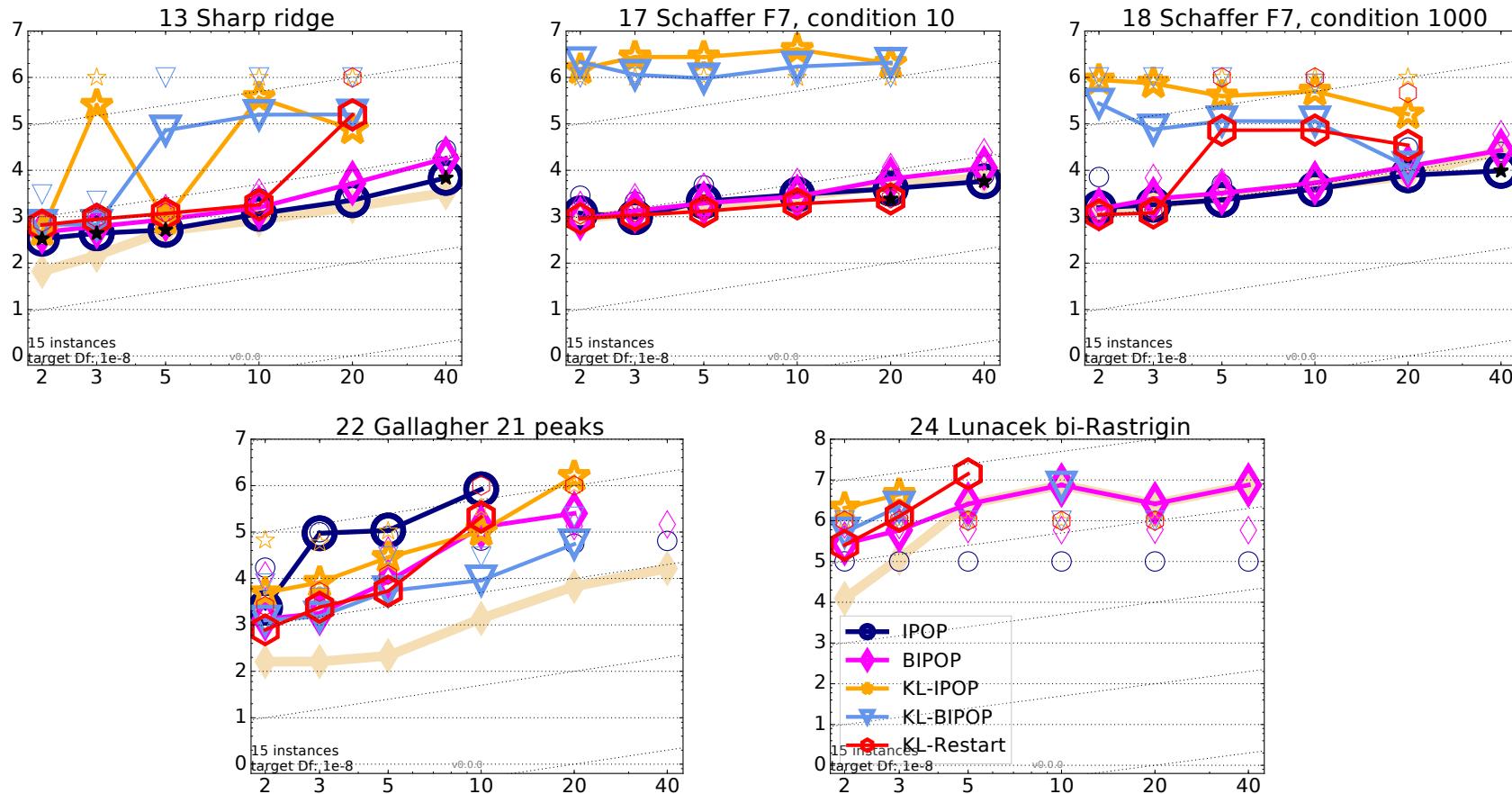


KL-Restart vs KL-IPOP vs KL-BIPOP



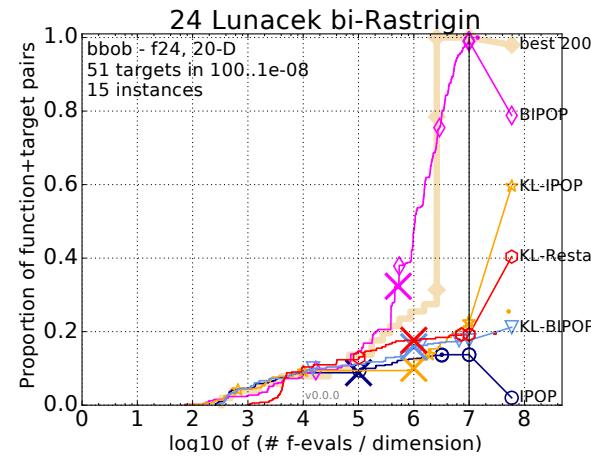
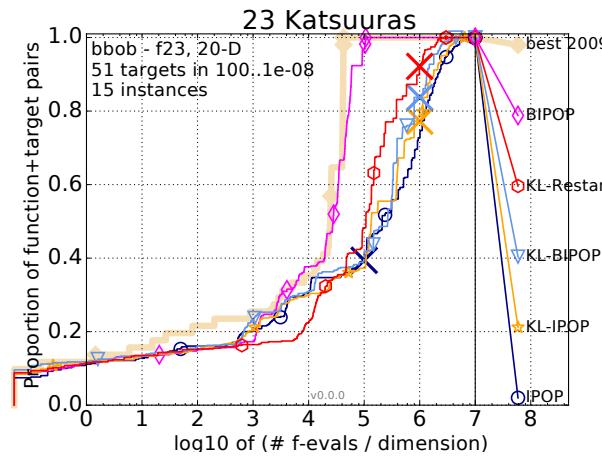
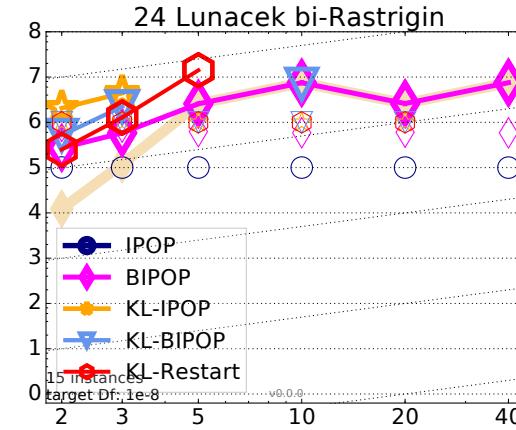
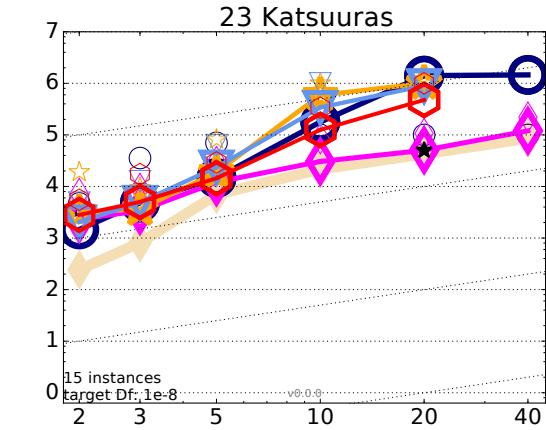
- **KL-Restart:** more FEs on unimodal functions due to the pop. size.
- f_{13} , f_{17} and f_{18} : **KL-IPOP** and **KL-BIPOP** suffered from early termination, while **KL-Restart** often finds the target function value at the first (re-)start, hence it works better than **KL-IPOP** and **KL-BIPOP**.

KL-IPOP vs IPOP



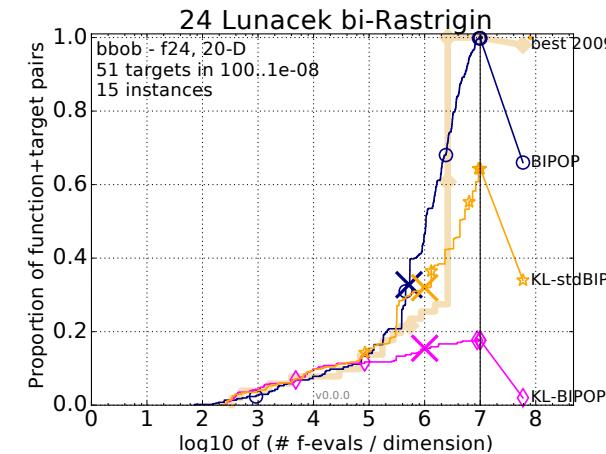
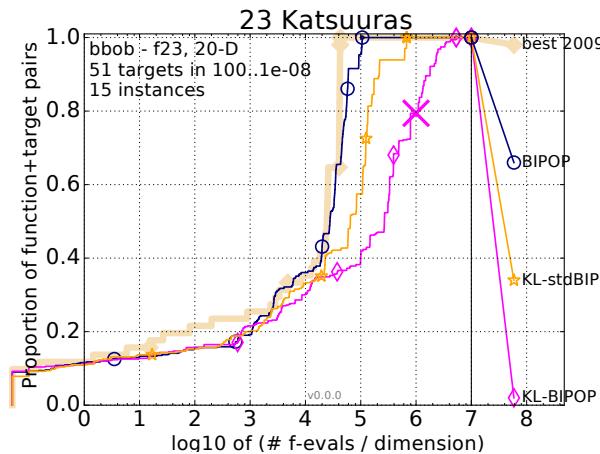
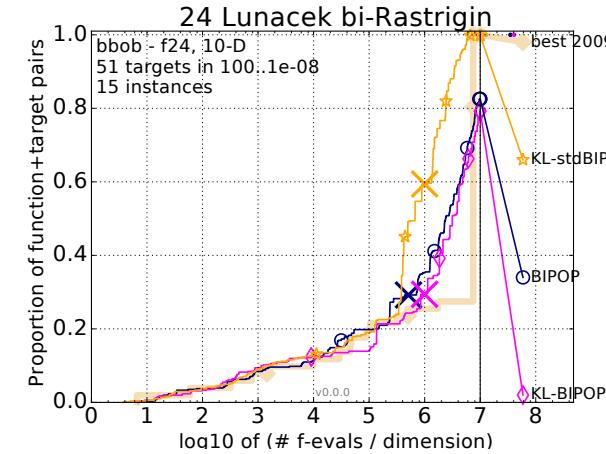
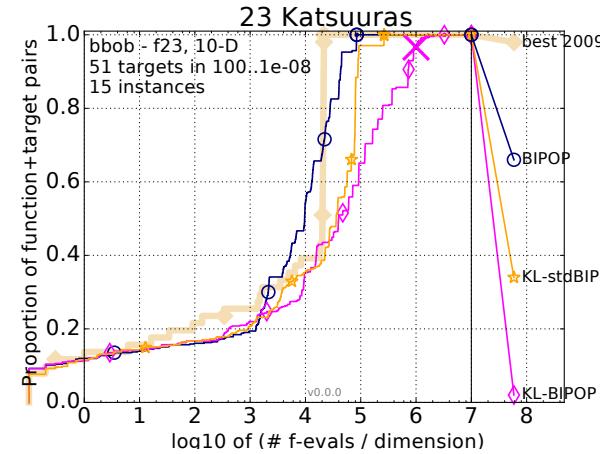
- **KL-IPOP** solved f_{22} , and f_{24} for $N \leq 5$ with fewer number of FEs than **IPOP**
- **IPOP** is significantly better on f_{13} , f_{17} and f_{18} than **KL-IPOP**
 - due to too early stopping

KL-BIPOP vs BIPOP



- difference between **KL-BIPOP** and **BIPOP** is similar to the difference between **KL-IPOP** and **IPOP**
- on f_{23} and f_{24} , **BIPOP** is superior to **KL-BIPOP**

KL-BIPOP vs BIPOP



KL-stdBIPOP: BIPOP + proposed termination mechanism

- **KL-stdBIPOP** performs better than **KL-BIPOP** on f_{23} and f_{24}
 - problem of **KL-BIPOP** on f_{23} and f_{24} is due to init. σ selection mechanism

Conclusion

Advantage

- promising performance on f_{22} (21 peak): weak global structure with a relatively small number of local minima

Disadvantage

- too early stopping on f_{13} (sharp ridge), f_{17} , f_{18} (Schaffer)
 - termination criterion needs to be improved
- initial step-size control mechanism not properly working for f_{23} and f_{24}
 - initial step-size control mechanism needs to be improved

